## FOG Photonics®INS8000 Ring Laser Gyro - Positioning Sensor



## **PRODUCT OVERVIEW**

INS8000 Ring Laser Gyro - Positioning Sensor systems is built in 0.008 degrees/hr high precision ring laser gyro, 10ug high precision quartz accelerometer, with the aid of the innovative inertial device error calibration compensation and strapdown navigation technology, it can achieve precision of 0.06 degrees self north seeking and 1nmile/hr autonomous navigation accuracy.

To ensure the compatibility requirements, the product is equipped with a new integrated navigation sensor together with "Starneto Fusion Engine (SFE)", the GNSS receiver can be external connected, making the use of the SFE block with GNSS, Optimal design of multi path interference, and with the auxiliary conditions of GNSS the product maintain the high accuracy output with much longer time.

In order to meet more applications, This device accept the external sensors such like Milemeter /DVL/Barometric altimeter.Multi sensors(Milemeter /DVL/Barometric altimeter) integrated into our INS8000 system, it guarantees this system with the high accuracy output fora long time.The INS8000 Systems have an excellent performance in application like Compass for vessels and high precision positioning and orientation(POS) application.

#### About Ring Laser Gyro Technology

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Optical technologies RLG & FOG sensing technologies form the basis of many of our motion sensors. Their role is to measure the rotation of a device in free space. Both technologies use a phase interferometry to achieve these rotational measurements. The RLG or the FOGs are arranged in a group of 3, and complimented with 3 matched accelerometers, to form a 6 Degree Of Freedom (DOF) inertial measurement unit (IMU).

RLG technology The monolithic RLGs used by FOG photonics are extremely stable over a range of temperatures and are available in 2 performance grades. A wide range of products, from the MiniRLG to the INS8000 are available with this technology. They are also available as positioning solutions, as they have embedded inertial navigation algorithms. When supplied with a DVL, the system can use the data from the DVL directly to aid the solution. Where most other technologies would have a hard time operating, RLGs are able to perform under adverse environmental conditions.

# **PRODUCT HIGHLIGHTS**:



#### Military grade device

Built in tactical inertial measurement device: 0.008° /hr Ring laser gyro, 10ug accelerometer



#### Autonomous Navigation High precision, Totally inertial navigation: 1nmile/hr



#### Self seeking north

High precision self seeking north: 0.06 degrees north seeking accuracy

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#### Good compatibility

Built-in GNSS Receiver: Support Compass B1、B2, and GSM Band2/3/8, TDS Band34/39, TDD-LTE Band38/39/40

#### **Compass function**

With Drift Free Compass function



Drift Free

Low noise, high update rate Solution(High bandwidth) high update rate : 200Hz data update rate



#### Support storage

With 16G data storage added,Support theSupport the storage of navigation data / raw data / external user data



#### Excellent scalability

Support a variety of external sensors (odometer /DVL/ altimeter etc.)



#### Flexible configuration protocol

NMEA0183 standard protocol output match with as many as 20 kinds of proprietary protocols



## Waterproof and dust proof

Waterproof and dust proof, IP CODE:IP67



Customizable selection Interface, storage, precision grade

# **TECHNICAL SPECIFICATIONS**

System accuracy		
Self seeking north	0.06SecL(1σ)	
Attitude accuracy	0.01° ( 1σ )	
Totally inertial navigation accuracy	1nmile/hr(CEP)	
GNSS Group Horizontal positioning accuracy	single-point L1/L2:1.2m(1σ)	
	DGPS : 0.4m ( 1σ )	
	RTK:2cm+1ppm(1σ)	
GNSS Group speed accuracy	0.02m/s(1σ)	
Combined Odometer Positioning precision	0.1%Mileage (depending on the external odometry accuracy)	
The Accuracy of heavy movement	5cm or 1%	

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	Start tim	10	≤10s		
Self seeking time			<5min		
	Measuring range				
Azim	uth measu		0° - 360°		
		uring range	±90°		
	-	suring range	±180°		
	Angular r		±300°/s		
	Acceleration		±10g		
Latitude		e	±85°		
Main device performance					
Gyro	Туре		Ring laser gyro		
	Measuring	gRange	±300°/s		
	Bias stabi	lity	0.008°/hr		
Accelerometer	Measuring	Range	±10g		
	Bias stabi	lity	≤10ug		
Data interface					
СОМ		2 channels ( RS2	32/RS422 Customizable configuration)、1channel RS232		
CAN2.0	)b		1 channel		
LAN			1channel		
		1 w	ay differential signal、2 ways of Single-Ended		
Pulse		Support PPS、EVENTMARK In/Out			
Auxiliary se	ensors	М	ilemeter /DVL/Barometric altimeter interface		
Storage ca	pacity		16GB(CUSTOMIZE)		
Data updat	e rate		200Hz(Customize)		
		Pov	ver Requirements		
Voltag	e		24V DC Rated ( 18-36V DC )		
Power consu	Imption		≤30W		
		Physi	cal characteristics ;		
Dimension			240mm×240mm×173mm		
Weigh	t		≤10kg		
		Environ	mental characteristics		
Vibratio	on		20~500Hz、Vibration acceleration:5g		
Impac	t		15g		
Operating temperature			-40°C - +71°C		
INGRESS PROTECTION			IP67		
MTBF 2000h		2000h			
Optional accessories					
Mileage me	ter Kit		Doppler speed radar / wheel speed sensor		
Barometric alti	meter Kit	10~1200Hpa , Res	olution 0.1Hpa , Height measurement accuracy10m (Max)		
RTK Different	ial radio		radio modem 433 MHz /900MHz/2.4GHz		
Navigation post processing software The processing results can reach level requirements of Surveying and		sults can reach level requirements of Surveying and mapping			

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## **Typical Applications**

		High dynamic range
Land field		High bandwidth measurement
	Unmanned aerial vehicle Aerial survey	Full temperature calibration compensation ( -40°C $\sim$ 60°C )
	Flight recorder	The optimization of Virbration environment precision
	Land positioning and orientation	INS/GNSS Integrated design
		The built-in 16G data storage
		Barometric altimeter combination
Air field		High-accuracy Inertial Measurement Unit(Miltary Grade)
	Intelligent unmanned vehicle	After surveying and mapping navigation processing function
	City surveying and mapping	High precision time synchronization
	High-speed railway track inspection	Ethernet/CAN interface
	Vehicular satellite communication	Support the standard 12V vehicle DC power source
		SFE Multi sensor fusion technology GNSS/odometer/RTK
		0.06°self seeking north
	Hydrological survey	High precious measurement technology
	Channel detection	of ship heavy movement
Sea field	Ship compass	Support connection of Ship carrying equipment(maxium 4 ways)
	Unmanned surface vehicle	IP67 protection grade
		Support the NMEA standard protocol
Underwater	Underwater vehicle	SFE the multi-sensor data fusion technology DVL/UBSL
field	Shaerwater venicie	Support the" Drift Free "compass function

#### Dimensions



